

Semi-Automatic Central-Chest Lymph-Node Definition from 3D MDCT Images

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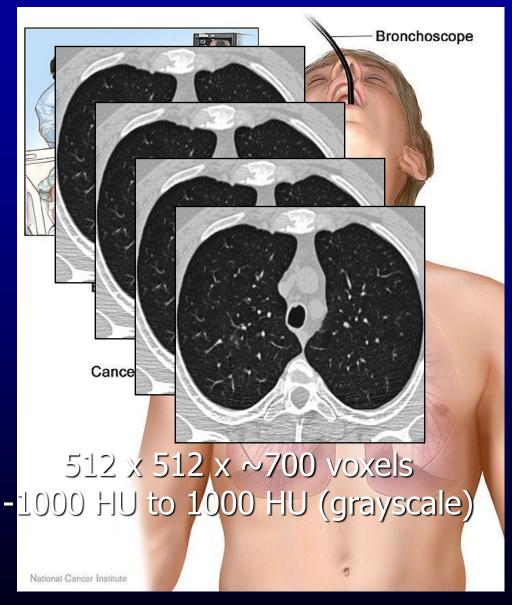
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Motivation

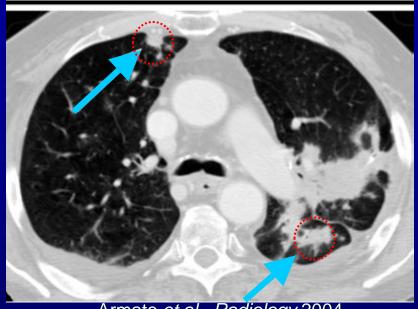


- Lung cancer is the leading cause of cancer death
- Early lung cancer detection could increase survival rate
- Diagnosis procedures:
 - 3D MDCT chest image assessment
 - Follow-on diagnostic bronchoscopy



Motivation

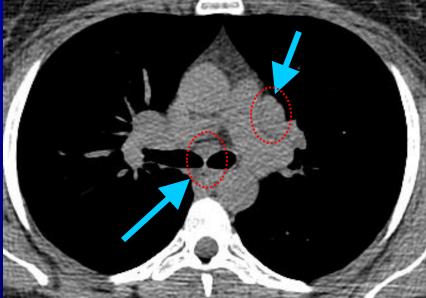




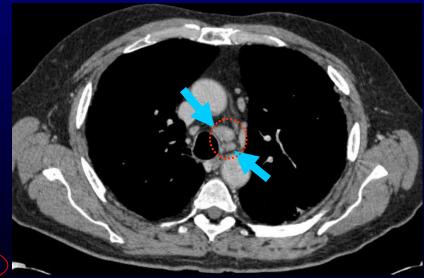
Armato et al., Radiology 2004

- ROIs involve complex phenomena
- Manual slice tracing not feasible
- Automatic methods
 - application dependent
- Semi-automatic methods
 - more practical

Live Wire



Subaortic and subcarinal lymph node (p2h012b)



Lower para-tracheal lymph node (IRB20349.3.3)

Prior Work



2D Live Wire:

- Mortensen and Barrett (Graphical Models and Medical Imaging 1998)
- Falcão et al. (Graphical Models and Medical Imaging 1998)
- Lu and Higgins (Int. J. CARS 2007)

3D Live Wire:

- Falcão and Udupa (Medical Image Analysis 2000)
- Hamarneh et al. (SPIE Medical Imaging 2005)
- König and Hesser (SPIE Medical Imaging 2005)
- Souza et al. (SPIE Medical Imaging 2006)
- Lu and Higgins (Int. J. CARS 2007)
- Poon et al. (SPIE Medical Imaging 2007 and CMIG 2008)

Prior Work



Cost Function:

$$l(p,q) = w_z f_z(q) + w_G f_G(q) + w_D f_D(p,q) + w_{Df} f_{Df}(p,q)$$

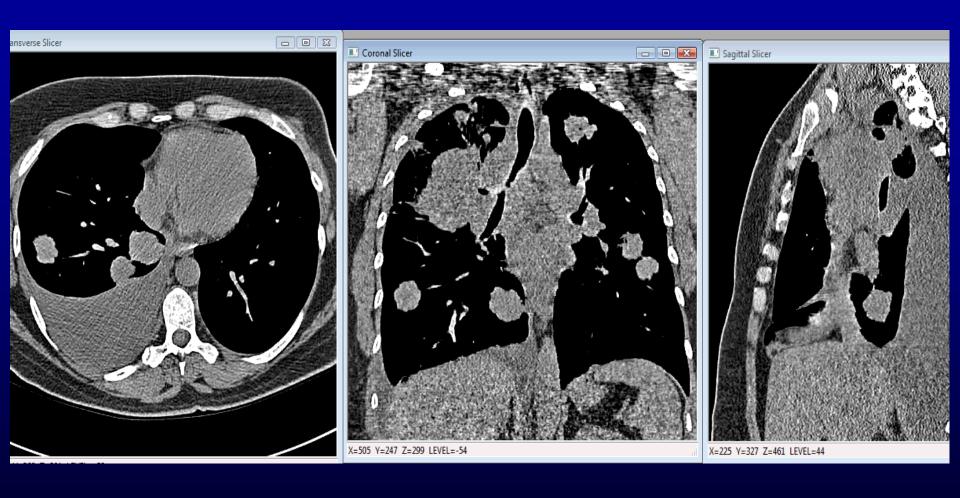
Dynamic Graphic Search:

```
Input:
  l(p,r)
Data Structures:
  N(p)
  e(p)
  g(p)
Output
Algorithm:
    q(s) \leftarrow 0; L \leftarrow s;
     While L \neq \Phi do begin
           pt \leftarrow min(L);
           e(p) \leftarrow TRUE;
4.
6.
           for each r \in N(p) such that \neg e(r) do begin
                  gtemp \leftarrow g(p) + l(p, r);
                  if r \in L and qtemp < q(r) then
10.
                          q(r) \leftarrow qtemp; pt(r) \leftarrow p;
11.
                 if r \notin L then begin
12.
                          g(r) \leftarrow gtemp; pt(r) \leftarrow p; L \leftarrow r;
13.
                  end
14.
           end
15. end
```



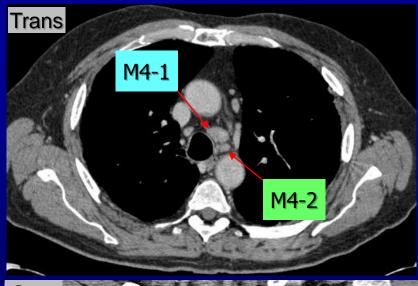
Prior Work

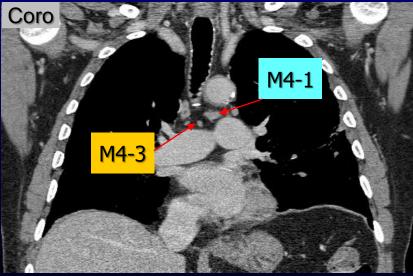




Segment ROI using 3D Live Wire

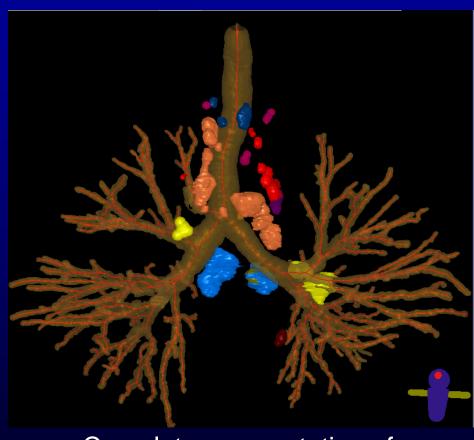
Central-Chest Lymph Nodes in 3D MDCT Image





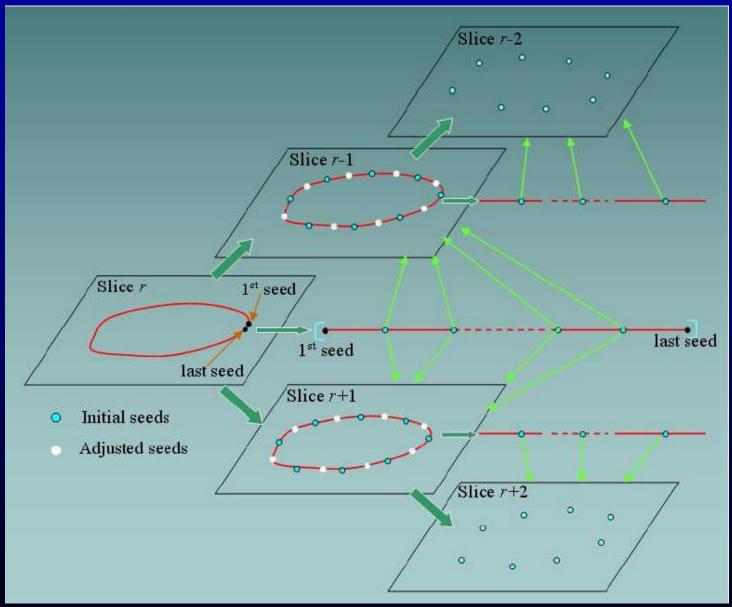
Typical lower paratracheal (M4) lymph nodes

Case IRB20349.3.3



Complete segmentation of central-chest lymph nodes







```
Inputs:
  i, j
                                             /* Iterators */
                                             /* Counter */
  r, B_{\tau}
                                             /* Reference section index and associated reference boundary */
                                            /* Min and max section indices for running automatic 3D
  i_{min}, i_{max}
                                                live wire in direction D_{lw}*/
                                            /* Seed set for section i, defined based on B<sub>ref</sub> */
  S_i
Data Structures:
                                            /* Reference object boundary for section i and its accumulated cost*/
  B_{ref}(i), c_{obj}
  \mathcal{L}_{obj}, N
                                            /* List of pixels along B<sub>obi</sub>(i) and its size. */
                                            /* Pixel-number and cost thresholds. By default, T_n = 16. */
  T_n, T_{cost}
Output
                                            /* Final ROI boundary for section i, i_{min} \le i \le i_{max} */
  B_{obj}(i)
Algorithm:
                                            /* Compute 2D boundaries for upper portion of ROI */
01. i = r + 1, k = 1
02. B_{obj} = B_{ref}(i) = B_r
                                            /* Use B_r as the reference section for section i */
      while i \leq i_{max} do
04.05.

do
if N \leq T then n = 4

                                            /* Reduce the size of S<sub>i</sub> if N is small enough */
06.
07.
08.
           else n = 8
           end while j \leq n do
09.
                 S(i) \leftarrow \mathcal{L}_{obj}(j * \frac{N}{n}) /* Select pixels evenly along B_{ref} */
10.
11.
           2DLW(S_i) \rightarrow B_{obj}(i), c_{obj} /* Connect seeds in S_i using 2D live wire and output section
                                               i's boundary and c_{obi} */
12.
           Update(\mathcal{L}_{obi}) \rightarrow \mathcal{L}_{obi}
                                            /* Add boundary pixels to Lobi starting from the midpoint
                                               from the segment between S_i(1) and S_i(1) on B_{obj} */
13.
           if k == 1 then
                                            /* Record the boundary cost as a reference for next iteration */
14.
             \tilde{c}_{obj} = c_{obj}
15.
16.
            k = k + 1
         while |c_{obj} - \tilde{c}_{obj}| > \frac{\tilde{c}_{obj}}{100}
17.
18.
         if Stopcheck() → FALSE then /* Process next section unless the boundary cost is
19.
           i = i + 1 and B_{ref}(i) = B_{obj} too small or stopping constraints are met. */
20.
     end
     i = r - 1, k = 1
                                            /* Compute 2D boundaries for lower portion of ROI */
     B_{obj} = B_{ref}(i) = B_r
                                            /* Use B<sub>r</sub> as the reference section for section i */
     while i \ge i_{min} do
25.
26.
           if N \leq T then n=4
                                            /* Reduce the size of S<sub>i</sub> if N is small enough */
27.
28.
29.
             else n = 4
           while j \leq n do
30.
                 S(i) \leftarrow \mathcal{L}_{obj}(j * \frac{N}{-}) /* Select pixels evenly along B_{ref} */
31.
32.
           2DLW(S_i) \rightarrow B_{obj}(i), c_{obj} /* Connect seeds in S_i using 2D live wire and output section
                                               i's boundary and c_{obi} */
33.
           Update(\mathcal{L}_{obj}) \rightarrow \mathcal{L}_{obj}
                                            /* Add boundary pixels to L<sub>obj</sub> starting from the mid point
                                               from the segment between \tilde{S}_i(1) and S_i(1) on B_{obj} */
            if k == 1 then
35.
             \tilde{c}_{obj} = c_{obj}
                                            /* Record the boundary cost as a reference for next iteration */
            end
38.
          while |c_{obj} - \tilde{c}_{obj}| > \frac{c_{obj}}{100}
39.
          if Stopcheck() → FALSE then /* Process next section unless the boundary cost is
           i = i - 1 and B_{ref}(i) = B_{obj} too small or stopping constraints are met. */
          end
```

- Adjust working area adaptively
- Refine seed set iteratively
- Terminate iterations when

$$|c_{obj} - \tilde{c}_{obj}| < \frac{c_{obj}}{100};$$

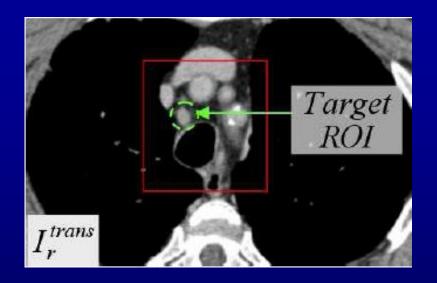
- Terminate 3D process when
 - Section limits reached
 - Boundary costs vary greatly

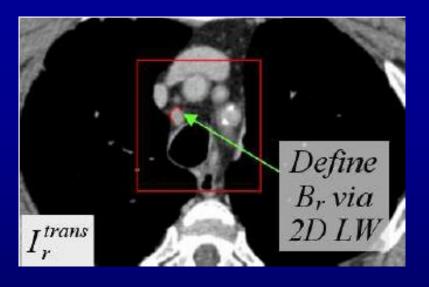
$$|c_{obj} - c_r| > \frac{c_r}{10}$$
.

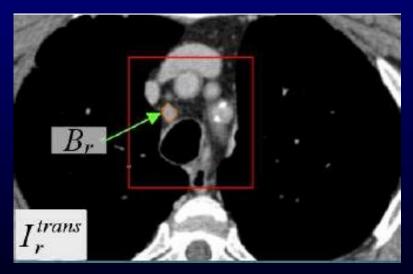
- Boundary is too small
- Segmented region is too small
- Intensity distribution varies greatly

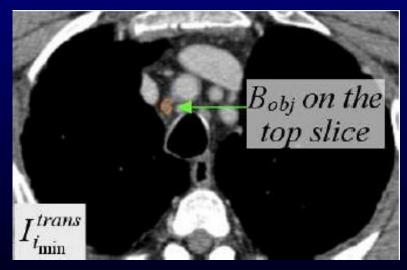
$$N_i^{out} > 0.5 \cdot N_i^{obj}$$





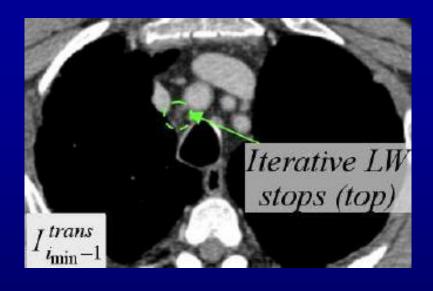


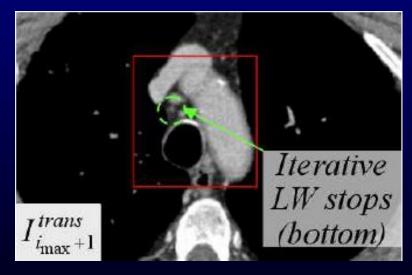


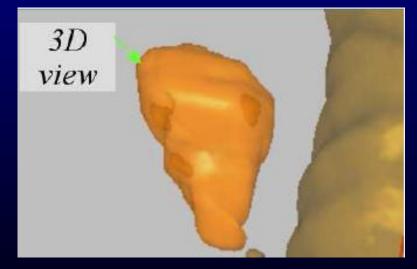






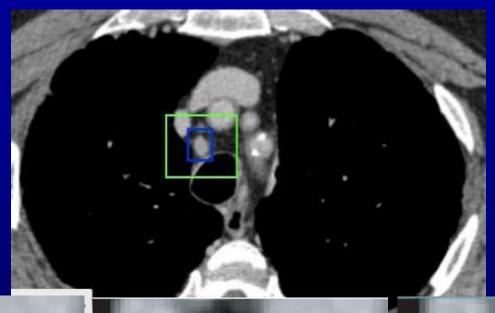


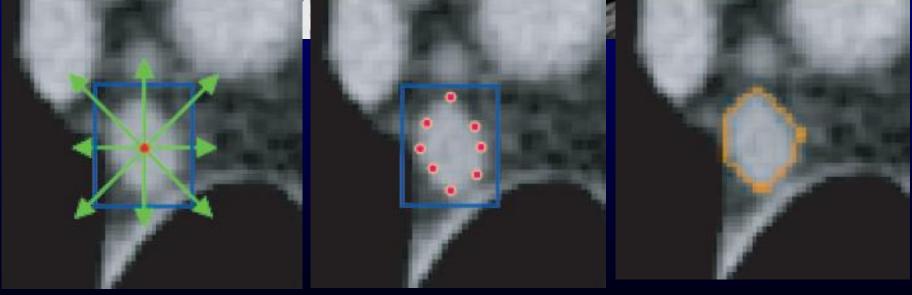




Single-Click Live Wire

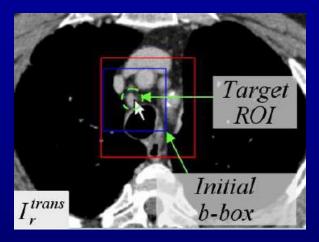


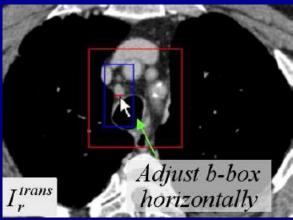


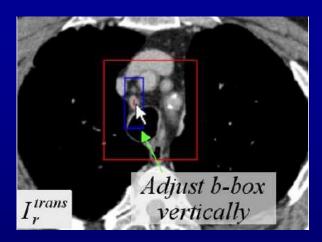


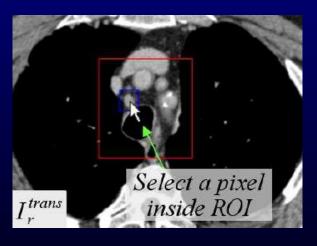
Single-Click Live Wire

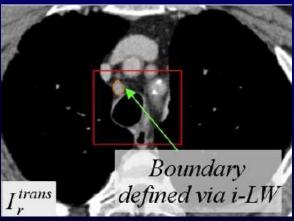


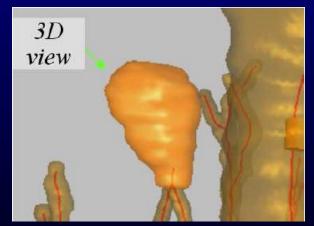






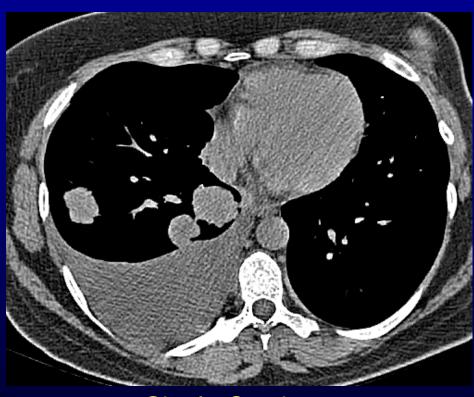






Single-Section and Single-Click LW







Single-Section

Single-Click

Performance Evaluation



MDCT Data:

	Voxel Dim.(mm)		# of slice	Contrast-	Observer	Scan	
Case	ΔX	ΔY	ΔZ	in scan	Enhanced	O	ID
21405_64	0.64	0.64	0.5	702	N	\mathcal{O}_1	1
20349_3_3	0.72	0.72	0.5	578	Ν	\mathcal{O}_1	2
20349_3_15	0.68	0.68	0.5	757	Ν	$\mathcal{O}_1,\mathcal{O}_2$	3
20349_3_27	0.67	0.67	0.5	752	Y	\mathcal{O}_1	4
21405_67	0.69	0.69	0.5	716	N	$\mathcal{O}_1,\mathcal{O}_2$	5

Computer - Dell Precision 650 workstation:

Dual Intel Xeon 3.2GHz, 3GB RAM, Windows XP

Results



Method	Single-Section	Single-Click	
Number of Nodes	50		
Success Rate	90 % (45/50)	80% (40/50)	
Accuracy	81±7%	79±8%	
Inter-Trial Reproducibility	88±7%	86±9%	
Processing Time	16±4s	20±5s	

Segmented Nodes:

Short-Axis Length: 5.8±1.5 mm

Long-Axis Length: 11±4.0 mm

■ Volume: 256±210 mm³

Number of Voxels: 1089±861

Comparison of Two Observers

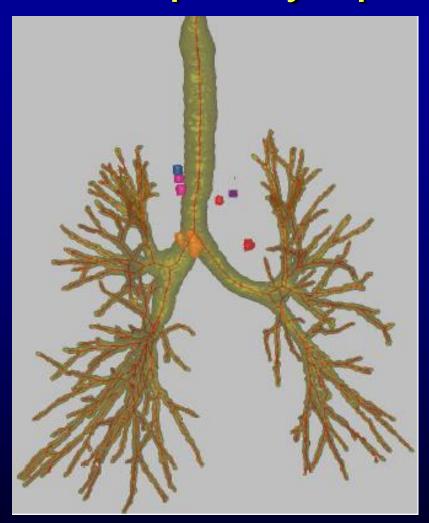


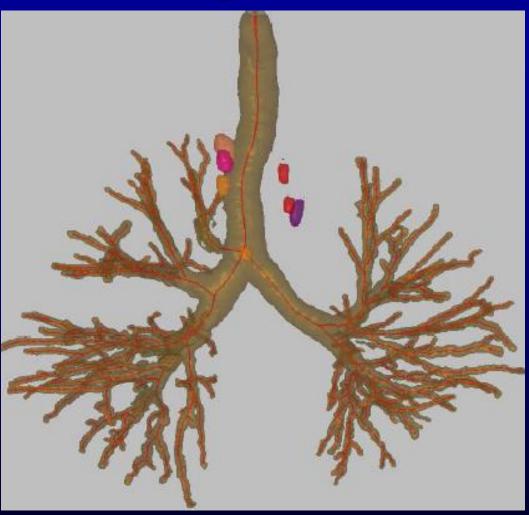
	20349	9.3.15	21405.67	
	O_1 O_2		O ₁	O_2
Accuracy	83%	80%	78%	79%
Reproducibility	87%	88%	89%	85%
Processing Time	16s	20s	19s	22s

Operator Independent

PENN<u>STATE</u>

Example Lymph Node Segmentations





21405.64

20349.3.3

Summary



Single-Section and Single-Click Live Wire

- Reduce human interaction
- > Efficient and reliable
- Operator independent
- Can handle typical lymph nodes and other ROIs
 - 90% Single-Section
 - 80% Single-Click





- NIH NCI grant #R01-CA074325
- Pinyo Taeprasartsit experiment participant

The Multidimensional Imaging Processing Lab at Penn State















Single-Section and Single-Click LW

Evaluation

Lymph node #: 50

Succ. Seg.: M_1 -45 (90%) M_2 -40 (80%)

Accuracy: >80%

Inter-trial Reprod.: >85%

	Processing Time (Second)				Axis Length (mm)		Volume	# of Voxel
Lymph Node	$\mathcal{M}_1,\mathcal{E}_1$	$\mathcal{M}_1,\mathcal{E}_2$	$\mathcal{M}_2,\mathcal{E}_1$	$\mathcal{M}_2,\mathcal{E}_2$	Short	Long	(mm^3)	in Lymph Node
μ	15	17	19	20	5.8	10.5	255.6	1089
σ	3.9	4.5	5.1	5.1	1.5	4.0	209.6	861.1
Min	7	9	7	9	3.7	5.5	63	273
Max	28	30	29	35	10.7	20.1	970	3796

	$a(\mathcal{M}_1, \mathcal{E}_1)$	$a(\mathcal{M}_1, \mathcal{E}_2)$	$r(\mathcal{M}_1,\mathcal{E}_1,\mathcal{E}_2)$	$a(\mathcal{M}_2,\mathcal{E}_1)$	$a(\mathcal{M}_2,\mathcal{E}_2)$	$r(\mathcal{M}_2,\mathcal{E}_1,\mathcal{E}_2)$
μ	81	81	88	79	79	86
σ	6.8	6.5	6.7	7.6	8.2	8.5
Min	62	69	66	63	54	60
Max	95	97	98	93	92	99

 M_1 , M_2 : Single-section and single-click LW; ε_1 , ε_2 : Trials; $a(M_i, \varepsilon_j)$: accuracy; $r(M_i, \varepsilon_j, \varepsilon_k)$: reproducibility

Single-Section and Single-Click LW Evaluation

	Processing Time (Second)							
	$\mathcal{M}_1,\mathcal{E}_1$	$\mathcal{M}_1, \mathcal{E}_1$ $\mathcal{M}_1, \mathcal{E}_2$ $\mathcal{M}_2, \mathcal{E}_1$ $\mathcal{M}_2, \mathcal{E}_3$						
$\mu_{\text{Scan 3}, \mathcal{O}_1}$	15	14	17	19				
$\mu_{\text{Scan 3},\mathcal{O}_2}$	16	19	20	21				
$\mu_{\text{Scan 5}, \mathcal{O}_1}$	19	20	19	20				
$\mu_{\text{Scan 5}, \mathcal{O}_2}$	15	18	26	27				
Overall	\bigcirc 15	17	19	20				

	Accuracy and Reproducibility (%)							
	$a(\mathcal{M}_1, \mathcal{E}_1)$	$a(\mathcal{M}_1, \mathcal{E}_2)$	$r(\mathcal{M}_1, \mathcal{E}_1, \mathcal{E}_2)$	$a(\mathcal{M}_2, \mathcal{E}_1)$	$a(\mathcal{M}_2, \mathcal{E}_2)$	$r(\mathcal{M}_2, \mathcal{E}_1, \mathcal{E}_2)$		
$\mu_{\text{Scan3},\mathcal{O}_1}$	84.3	85.5	88.5	81.2	80.5	85.6		
$\mu_{ ext{Scan3},\mathcal{O}_2}$	78.3	78.5	82.9	79.5	78.2	86.2		
$\mu_{\text{Scan5},\mathcal{O}_1}$	78.8	79.1	91.8	76.3	77.1	85.6		
$\mu_{\text{Scan5},\mathcal{O}_2}$	80.9	81.1	89.8	77.1	80.1	85.2		
Overall	80.7	81.2	88.3	79.2	79.3	85.6		